# Configurable Software Verification based on Slicing Abstractions

Martin Spießl

LMU Munich







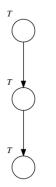


#### Outline

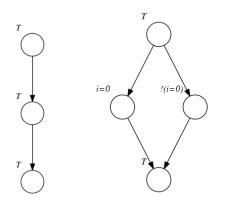
- Basic Idea
- Example Program
  - Splitting via Interpolants (Kojak)
  - Slicing Abstractions (SLAB)
- Fitting Kojak into the CPACHECKER Framework
  - CPA Algorithm
  - CEGAR Algorithm
  - Adjustable-Block Encoding
- Fitting SLAB into the CPACHECKER Framework
  - Flexible-Block Encoding
- Evaluation

#### Summary

## Slicing Abstractions Idea

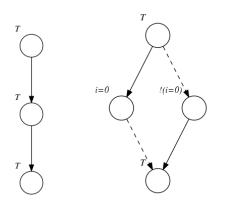


## Slicing Abstractions Idea



- Split abstraction state into two states
- ► Disjunction of the splitted states represent the same concrete states as in the original state ⇒ soundness
- Incoming & outgoing edges have to be copied

## Slicing Abstractions Idea



- Split abstraction state into two states
- ► Disjunction of the splitted states represent the same concrete states as in the original state ⇒ soundness
- Incoming & outgoing edges have to be copied
- Slice by removing infeasible edges
- disconnected subgraphs can be removed

# Slicing Abstractions in Software Model Checking

#### (2007) Slicing Abstractions

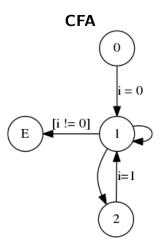
- program counter (if present) tracked symbolically
- motivated by predicate abstraction
- Implementation: SLAB

#### (2012) Splitting via Interpolants

- makes use of control-flow graph
  - $\Rightarrow$  symbolic program counter not needed
- motivated by SLAB
- uses Large-Block Encoding
- Implementation: Ultimate Kojak

# Example Program

#### example.c



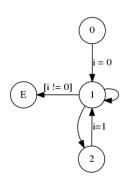
#### Basic Steps:

- **Split:** Split states along the error path using interpolants
- **Slice:** Remove infeasible edges

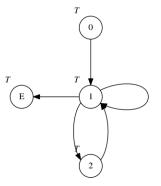
#### Termination

- when finding a real counterexample: return false
- when all error states are disconnected: return true

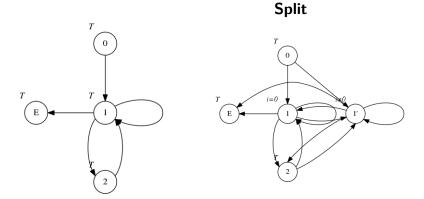
#### Initial Abstract Model

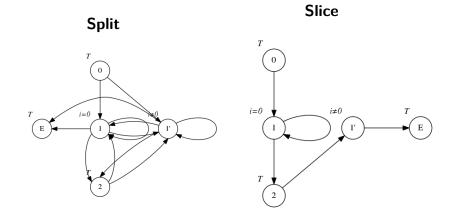


**CFA** 



#### Initial Abstract Model



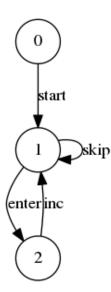


#### Basic Steps:

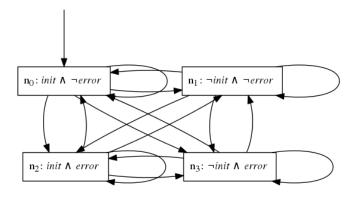
Similar to Kojak, but treat program counter symbolically
 Special initial abstract model with predicates *init* and *error*

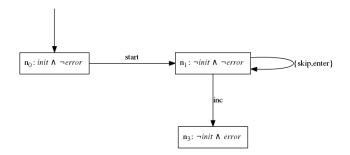
#### Termination

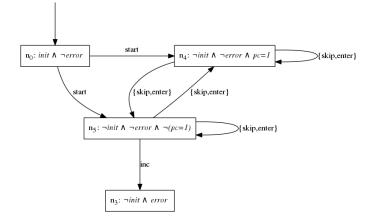
- when finding a feasible counterexample: return false
- when no states with predicate error are left: return true



init	pc = 0
error	$pc = 1 \land i \neq 0$
start	$pc = 0 \land pc' = 1 \land i' = 0$
skip	$pc = 1 \wedge pc' = 1$
enter	$pc = 1 \wedge pc' = 2$
inc	$pc = 2 \land pc' = 1 \land i' = 1$







#### Implementation of Kojak in CPACHECKER

- Entirely new CPA is NOT needed, instead we reuse the CPA of predicate abstraction with adjustable-block encoding (CPA<sub>ABE</sub>)
- Path formulas need to be constructed separately
- Special choice of CPA- and CEGAR algorithm inputs
- Refinement procedure that implements splitting and slicing
- Refinement operates on abstract reachability graph (ARG)
  ⇒ lots of graph manipulation, esp. for ABE

1:	while waitlist $\neq \varnothing$ do
2:	choose $e$ from waitlist
3:	waitlist := waitlist $\setminus \{e\}$
4:	for all $e'$ with $e \rightarrow e'$ do
5:	for all $e'' \in$ reached <b>do</b>
6:	<pre>// combine with existing abstract state</pre>
7:	$e_{new} := merge(e, e'')$
8:	if $e_{new} \neq e''$ then
9:	$waitlist := (waitlist \cup \{e_{new}\}) \setminus \{e''\}$
10:	$reached := (reached \cup \{e_{new}\}) \setminus \{e''\}$
11:	if $\neg$ stop $(e',$ reached) then
12:	if $abort(e')$ then
13:	return (reached, waitlist)
14:	$waitlist := waitlist \cup \{e'\}$
15:	$reached := reached \cup \{e'\}$
16:	return (reached, waitlist)

\* original algorithm also contains precision, removed here for brevity

1:	while waitlist $\neq \emptyset$ do
2:	choose $e$ from waitlist
3:	$waitlist := waitlist \setminus \{e\}$
4:	for all $e'$ with $e \rightarrow e'$ do
5:	for all $e'' \in$ reached <b>do</b>
6:	<pre>// combine with existing abstract state</pre>
7:	$e_{new} := merge(e, e'')$
8:	if $e_{new} \neq e''$ then
9:	$waitlist := (waitlist \cup \{e_{new}\}) \setminus \{e''\}$
10:	$reached := (reached \cup \{e_{new}\}) \setminus \{e''\}$
11:	if $\neg$ stop $(e',$ reached) then
12:	if $abort(e')$ then
13:	return (reached, waitlist)
14:	$waitlist := waitlist \cup \{e'\}$
15:	$reached := reached \cup \{e'\}$
16:	return (reached, waitlist)

merge operator: Merge states at same location in the ARG until parent sets are equal

#### \* original algorithm also contains precision, removed here for brevity

LMU Munich

1:	while waitlist $\neq \emptyset$ do
2:	choose $e$ from waitlist
3:	waitlist := waitlist $\setminus \{e\}$
4:	for all $e'$ with $e \rightarrow e'$ do
5:	for all $e'' \in$ reached <b>do</b>
6:	<pre>// combine with existing abstract state</pre>
7:	$e_{new} := merge(e, e'')$
8:	if $e_{new} \neq e''$ then
9:	$waitlist := (waitlist \cup \{e_{new}\}) \setminus \{e''\}$
10:	$reached := (reached \cup \{e_{new}\}) \setminus \{e''\}$
11:	if $\neg$ stop $(e',$ reached) then
12:	if $abort(e')$ then
13:	return (reached, waitlist)
14:	$waitlist := waitlist \cup \{e'\}$
15:	$reached := reached \cup \{e'\}$
16:	return (reached, waitlist)

merge operator:

Merge states at same location in the ARG until parent sets are equal

 stop<sub>sep</sub> is sufficient, since all states have abstraction formula T

\* original algorithm also contains precision, removed here for brevity

LMU Munich

1:	while waitlist $\neq \varnothing$ do
2:	choose $e$ from waitlist
3:	$waitlist := waitlist \setminus \{e\}$
4:	for all $e'$ with $e \rightsquigarrow e'$ do
5:	for all $e'' \in$ reached do
6:	<pre>// combine with existing abstract state</pre>
7:	$e_{new} := merge(e, e'')$
8:	if $e_{new} \neq e''$ then
9:	waitlist := (waitlist $\cup \{e_{new}\}) \setminus \{e''\}$
10:	$reached := (reached \cup \{e_{new}\}) \setminus \{e''\}$
11:	if $\neg$ stop $(e',$ reached) then
12:	if $abort(e')$ then
13:	return (reached, waitlist)
14:	$waitlist := waitlist \cup \{e'\}$
15:	$reached := reached \cup \{e'\}$
16:	return (reached, waitlist)

• merge operator:

Merge states at same location in the ARG until parent sets are equal

- stop<sub>sep</sub> is sufficient, since all states have abstraction formula ⊤
- Global Refinement: abort (e') always returns ⊥

 $\ast$  original algorithm also contains precision, removed here for brevity

# Slicing Abstractions as CEGAR Refinement Strategy

#### 1: **loop**

- 2:  $(reached, waitlist) := CPA^*(\mathbb{D}, reached, waitlist, abort)$
- 3: **if**  $\exists e \in$ reached : isTargetState(e) **then**
- 4: (reached, waitlist) := refine(reached, waitlist)
- 5: **if**  $\exists e \in \mathsf{reached} : \mathsf{isTargetState}(e)$  **then**
- 6: return false
- 7: else
- 8: return true

# Slicing Abstractions as CEGAR Refinement Strategy

**Input:** a CPA  $\mathbb{D} = (D, \rightsquigarrow, \text{merge}, \text{stop})$ , an initial abstract state  $e_0 \in E$ , a function refine :  $\mathcal{P}(E) \times \mathcal{P}(E) \rightarrow \mathcal{P}(E) \times \mathcal{P}(E)$ , a function abort :  $E \rightarrow \mathbb{B}$ a function isTargetState :  $E \rightarrow \mathbb{B}$ 

#### 1: **loop**

- 2:  $(reached, waitlist) := CPA^*(\mathbb{D}, reached, waitlist, abort)$
- 3: **if**  $\exists e \in$ reached : isTargetState(e) **then**
- 4: (reached, waitlist) := refine(reached, waitlist)
- 5: **if**  $\exists e \in \mathsf{reached} : \mathsf{isTargetState}(e)$  **then**
- 6: return false
- 7: else
- 8: return true

 Formulate splitting and slicing as CEGAR refinement strategy (called in refine)

# Slicing Abstractions as CEGAR Refinement Strategy

#### 1: **loop**

- 2:  $(reached, waitlist) := CPA^*(\mathbb{D}, reached, waitlist, abort)$
- 3: **if**  $\exists e \in \mathsf{reached} : \mathsf{isTargetState}(e)$  **then**
- $4: \qquad (\mathsf{reached},\mathsf{waitlist}) := \frac{\mathsf{refine}}{\mathsf{reached}}, \mathsf{waitlist})$
- 5: **if**  $\exists e \in \mathsf{reached} : \mathsf{isTargetState}(e)$  **then**
- 6: return false
- 7: else
- 8: return true

- Formulate splitting and slicing as CEGAR refinement strategy (called in refine)
  - Strategy repeats splitting and slicing until feasible counterexample is found or all error states have been removed

# Slicing Abstractions as CEGAR Refinement Strategy

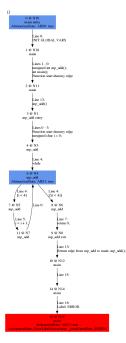
#### 1: **loop**

- 2:  $(reached, waitlist) := CPA^*(\mathbb{D}, reached, waitlist, abort)$
- 3: **if**  $\exists e \in \mathsf{reached} : \mathsf{isTargetState}(e)$  **then**
- 4: (reached, waitlist) := refine(reached, waitlist)
- 5: **if**  $\exists e \in \mathsf{reached} : \mathsf{isTargetState}(e)$  **then**
- 6: return false
- 7: else
- 8: return true

- Formulate splitting and slicing as CEGAR refinement strategy (called in refine)
  - Strategy repeats splitting and slicing until feasible counterexample is found or all error states have been removed
- ► ⇒ CPA\* and refine will only be called once in this setup

#### Adjustable-Block Encoding

- ABE as flexible replacement for LBE (used by Kojak)
- PredicateCPA is already used to store abstraction formulas
  ABE from PredicateCPA can be reused
- However: block formulas from PredicateCPA cannot be used because the abstraction states in the ARG do not form a tree (previous abstraction state will be ambigious)
   ⇒ dynamically recalculate them
- Loss of tree shape in ARG causes other problems
- Non-abstraction states have to be copied when splitting states (example on next slide)









#### Adjustments for SLAB

- We need a custom transfer relation in the PredicateCPA ⇒Generates successors: *init* ∧ *error*,¬*init* ∧ *error*,...
- Adapt path-formula creation to generate formulas for program counter
- We need a way to store multiple CFA edges for the transition between two ARG states
   ⇒ refinement refine<sub>SliAbs</sub> needs to be aware of this
- Presence of LocationCPA is sometimes assumed in CPACHECKER

 $\Rightarrow$  add right handling for when this is not the case

 Apart from that, we can use the same procedure as for Kojak

# Flexible-Block Encoding

#### Problem:

- How can we add ABE to SLAB?
- We cannot form blocks in the initial abstract model

#### Solution: Flexible-Block Encoding (FBE)

- Use a blk operator similar to that of ABE
- Convert abstraction states after each refinement step
- Fixed-point iteration: apply blk, slice, repeat ...
- FBE can also be used for Kojak

## Interprocedural Analysis

#### For Kojak

- Add CallstackCPA that tracks the call stack
- effectively results in function inlining in the initial abstract model
  - $\Rightarrow$  sound and precise, but potentially inefficient
- obviously fails for recursive procedures (ULTIMATE KOJAK supports recursion via nested word automata)

## Interprocedural Analysis

#### For SLAB

- Simply adding a CallstackCPA would lead to an infinite initial abstract model
- Fix: CallstackCPA would need to be aware of whether a function can be called from the current context
- This is then similar to a recursive CFG as used by ULTIMATE KOJAK
  - $\Rightarrow$  potentially extendable for recursion

#### Benchmark

#### Tasks

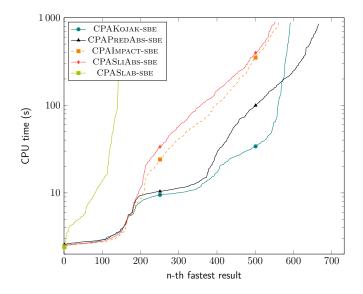
 2942 tasks from the reach-safety category of the 2018 Competition on Software Verification (SVCOMP18)

10 subcategories

#### Environment (identical to SVCOMP18)

- Hosts: Intel Xeon E3-1230 v5 CPU, 8 processing units, 33 GB of memory, Ubuntu 16.04 / Linux kernel 4.4.0-128
- Limits: 900s, 15 GB, 8 processing units
- BENCHEXEC is used for run isolation, resource measurement and limitation

#### Comparision using Single-Block Encoding

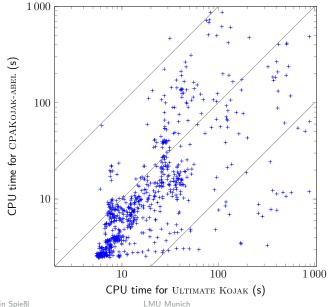


## Comparision using Single-Block Encoding

#### Quantile-Plot Insights

- Replacing the refiner of IMPACT by our refine<sub>SliAbs</sub> does not change the results significantly (apart from minor overhead of splitting/slicing)
- CPAKOJAK-ABEL is faster than CPAPREDABS-SBE, but solves less tasks (differences are mostly due to product-lines category)
- CPASLAB-SBE takes too many solver calls to discover the control flow
- ULTIMATE KOJAK is not shown since there is no option to disable LBE

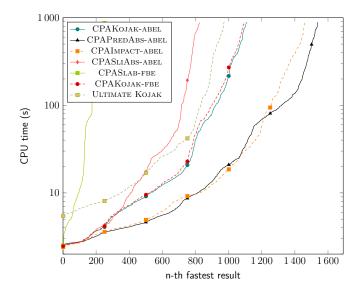
#### ULTIMATE KOJAK VS. CPAKOJAK-ABEL



Martin Spießl

24 / 28

### Comparison using Adjustable-Block Encoding

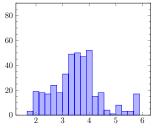


### Comparision using Adjustable-Block Encoding

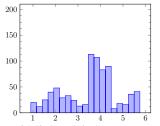
#### Quantile-Plot Insights

- CPAKOJAK-ABEL outperforms ULTIMATE KOJAK (however: not in all subcategories)
- CPAKOJAK-ABEL outperformed by CPAPREDABS-ABEL and CPAIMPACT-ABEL
- CPASLAB-FBE is better than CPASLAB-SBE but has still same problem (too many solver calls for control flow)
- CPAKOJAK-FBE is no improvement compared to CPAKOJAK-ABEL

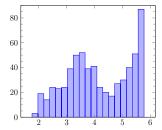
### Solver Calls for Slicing



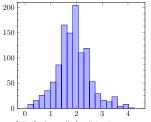
 $\log_{10}$  of # of solver calls for slicing in CPASLAB-SBE



 $\log_{10}$  of # of solver calls for slicing in CPAKOJAK-SBE



 $\log_{10}$  of # of solver calls for slicing in  ${\rm CPASLAB-FBE}$ 



 $\log_{10}$  of # of solver calls for slicing in CPAKOJAK-ABEL

### Summary

- CPACHECKER can now do analyses comparable to Kojak and SLAB
- Our implementation of Kojak is not worse than ULTIMATE KOJAK
- Cost of slicing edges becomes dominant with increasing block size
- Direct usage of control-flow information is important when dealing with programs
- Still a lot of open questions for future work, e.g. recursion, function handling for SLAB, increasing slicing performance, concurrency, witness generation/validation, ...

# BACKUP

	Ulttimate Kojak	CPAK0JAK-ABEL-LIN	CPAK0JAK-ABEL	CPAK0JAK-SBE	CPAK0JAK-FBE	CPAIMPACT-ABEL	CPAIMPACT-SBE	CPAP REDABS-ABEL	CPAP REDABS-SBE	CPASLIABS-ABEL	CPASLIABS-SBE	CPASLAB-SBE	CPASLAB-FBE
arrays (167 tasks)	10				-							_	_
correct results	10	11	4	3	5	4	3	6	6	3	3	7	5
bitvectors (50 tasks) correct results	19	19	36	27	33	34	30	39	28	31	30	17	19
control flow (94 tasks)	19	19	30	21	- 33	- 34	30	- 39	28	31	30	17	19
correct results	31	68	59	44	52	55	24	62	34	39	23	4	8
ECA (1149 tasks)													
correct results	328	235	200	6	201	450	3	477	4	241	3	1	3
floats (172 tasks)													
correct results	33	53	34	6	34	28	6	91	11	27	5	2	2
heap (181 tasks)													
correct results	100	117	108	94	103	110	94	114	94	100	94	54	77
loops (163 tasks)													
correct results	96	103	76	73	74	74	71	82	69	71	68	64	63
product lines (597 tasks)													
correct results	295	462	463	327	463	578	309	551	406	203	304	0	78
recursive (96 tasks)													
correct results	45	0	0	0	0	0	0	0	0	0	0	0	0
sequentialized (273 tasks) correct results	17	155	131	12	131	127	22	116	14	109	23	1	2
total (2942)	17	155	131	12	131	127	22	110	14	109	23	1	2
correct results	974	1223	1111	592	1096	1460	562	1538	666	824	553	150	257
correct true	664	680	623	368	623	785	291	915	369	391	281	88	179
correct false	310	543	488	224	473	675	291	623	297	433	272	62	78
incorrect results	0	226	100	1	1	1	2	2	1	1	2	31	29
	u ^	· *											

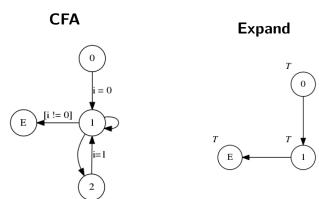
Martin Spießl

### Basic Steps:

- **Expand:** Unwind the CFA until error state is discovered
- Refine: Use interpolation to remove infeasible states from abstraction
- **Cover:** Calculate coverage relation to reach fixed point

#### Termination

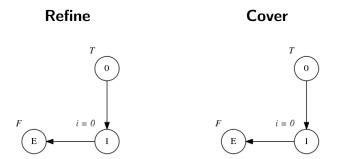
when finding a feasible counterexample: return false
 when fixed point is reached / all states explored: return true

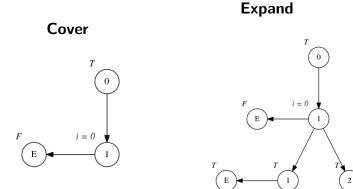


Expand Refine Τ 0 F Τ Т Е Ε

T 0

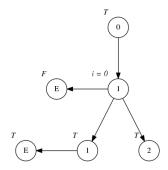
i = 0

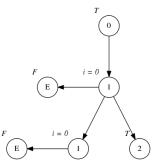




Expand

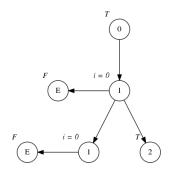


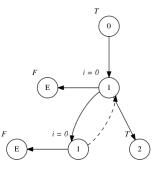




Refine

Cover





Cover

Expand

